# On twisted Riemannian extensions associated with Szabó metrics 

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#### Abstract

Let $M$ be an $n$-dimensional manifold with a torsion free affine connection $\nabla$ and let $T^{*} M$ be the cotangent bundle. In this paper, we consider some of the geometric aspects of a twisted Riemannian extension which provide a link between the affine geometry of $(M, \nabla)$ and the neutral signature pseudo-Riemannian geometry of $T^{*} M$. We investigate the spectral geometry of the Szabó operator on $M$ and on $T^{*} M$.


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## 1. Introduction

Let $M$ be an $n$-dimensional manifold with a torsion free affine connection and let $T^{*} M$ be the cotangent bundle. In [11], Patterson and Walker introduced the notion of Riemann extensions and showed how a pseudo-Riemannian metric can be given to the $2 n$ dimensional cotangent bundle of an $n$-dimensional manifold with given non-Riemannian structure. They showed that Riemann extensions provide a solution of the general problem of embedding a manifold $M$ carrying a given structure in a manifold $N$ carrying another structure. The embedding is carried out in such a way that the structure on $N$ induces in a natural way the given structure on $M$. The Riemann extensions can be constructed with the help of the coefficients of the affine connection.

[^0]The Riemann extensions which are pseudo-Riemannian metrics of neutral neutral signature show its importance in relation to the Osserman manifolds [7], Walker manifolds [1] and non-Lorentzian geometry. In [3], the authors generalized the usual Riemannian extensions to the so-called twisted Riemannian extensions. The latter is also called deformed Riemannian extension (see [6] for more details). In [1, 6], the authors studied the spectral geometry of the Jacobi operator and skew-symmetric curvature operator both on $M$ and on $T^{*} M$. The results on these operators are detailed, for instance, in [6, Theorem 2.15].

In this paper, we shall consider some of the geometric aspects of twisted Riemannian extensions and we will investigate the spectral geometry of the Szabó operator on $M$ and on $T^{*} M$. Note that the Szabó operator has not been deeply studied like the Jacobi and skew-symmetric curvature operators.

Our paper is organized as follows. In the section 2, we recall some basic definitions and results on the classical Riemannian extension and the twisted Riemannian extension developed in the books [1, 6]. Finally in section 3, we investigates the spectral geometry of the Szabó operator on $M$ and on $T^{*} M$, and we construct two examples of pseudoRiemannian Szabó metrics of signature ( 3,3 ), using the classical and twisted Riemannian extensions, whose Szabó operators are nilpotent.

Throughout this paper, all manifolds, tensors fields and connections are always assumed to be differentiable of class $\mathcal{C}^{\infty}$.

## 2. Twisted Riemannian extension

Let $(M, \nabla)$ be an $n$-dimensional affine manifold and $T^{*} M$ be its cotangent bundle and let $\pi: T^{*} M \rightarrow M$ be the natural projection defined by $\pi(p, \omega)=p \in M$ and $(p, \omega) \in T^{*} M$. A system of local coordinates $\left(U, u_{i}\right), i=1, \cdots, n$ around $p \in M$ induces a system of local coordinates $\left(\pi^{-1}(U), u_{i}, u_{i^{\prime}}=\omega_{i}\right), i^{\prime}=n+i=n+1, \cdots, 2 n$ around $(p, \omega) \in T^{*} M$, where $u_{i^{\prime}}=\omega_{i}$ are components of covectors $\omega$ in each cotangent space $T_{p}^{*} M, p \in U$ with respect to the natural coframe $\left\{d u^{i}\right\}$. If we use the notation $\partial_{i}=\frac{\partial}{\partial u_{i}}$ and $\partial_{i^{\prime}}=\frac{\partial}{\partial \omega_{i}}, i=i, \cdots, n$ then at each point $(p, \omega) \in T^{*} M$, its follows that

$$
\left\{\left(\partial_{1}\right)_{(p, \omega)}, \cdots,\left(\partial_{n}\right)_{(p, \omega)},\left(\partial_{1^{\prime}}\right)_{(p, \omega)}, \cdots,\left(\partial_{n^{\prime}}\right)_{(p, \omega)}\right\},
$$

is a basis for the tangent space $\left(T^{*} M\right)_{(p, \omega)}$.
For each vector field $X$ on $M$, define a function $\iota X: T^{*} M \longrightarrow \mathbb{R}$ by

$$
\iota X(p, \omega)=\omega\left(X_{p}\right) .
$$

This function is locally expressed by,

$$
\iota X\left(u_{i}, u_{i^{\prime}}\right)=u_{i^{\prime}} X^{i},
$$

for all $X=X^{i} \partial_{i}$. Vector fields on $T^{*} M$ are characterized by their actions on functions $\iota X$. The complete lift $X^{C}$ of a vector field $X$ on $M$ to $T^{*} M$ is characterized by the identity

$$
X^{C}(\iota Z)=\iota[X, Z], \quad \text { for all } \quad Z \in \Gamma(T M)
$$

Moreover, since a $(0, s)$-tensor field on $M$ is characterized by its evaluation on complete lifts of vector fields on $M$, for each tensor field $T$ of type $(1,1)$ on $M$, we define a 1-form $\iota T$ on $T^{*} M$ which is characterized by the identity

$$
\iota T\left(X^{C}\right)=\iota(T X)
$$

For more details on the geometry of cotangent bundle, we refer to the book of Yano and Ishihara [13].

Let $\nabla$ be a torsion free affine connection on an $n$-dimensional affine manifold $M$. The Riemannian extension $g_{\nabla}$ is the pseudo-Riemannian metric on $T^{*} M$ of neutral signature $(n, n)$ characterized by the identity $[1,6]$

$$
g_{\nabla}\left(X^{C}, Y^{C}\right)=-\iota\left(\nabla_{X} Y+\nabla_{Y} X\right)
$$

In the locally induced coordinates $\left(u_{i}, u_{i^{\prime}}\right)$ on $\pi^{-1}(U) \subset T^{*} M$, the Riemannian extension is expressed by

$$
g_{\nabla}=\left(\begin{array}{cc}
-2 u_{k^{\prime}} \Gamma_{i j}^{k} & \delta_{i}^{j}  \tag{2.1}\\
\delta_{i}^{j} & 0
\end{array}\right)
$$

with respect to $\left\{\partial_{1}, \cdots, \partial_{n}, \partial_{1^{\prime}}, \cdots, \partial_{n^{\prime}}\right\}\left(i, j, k=1, \cdots, n ; k^{\prime}=k+n\right)$, where $\Gamma_{i j}^{k}$ are the Christoffel symbols of the torsion free affine connection $\nabla$ with respect to ( $U, u_{i}$ ) on $M$. Some properties of the affine connection $\nabla$ can be investigated by means of the corresponding properties of the Riemannian extension $g_{\nabla}$. For instance, $(M, \nabla)$ is locally symmetric if and only if ( $T^{*} M, g_{\nabla}$ ) is locally symmetric [6]. Furthermore ( $M, \nabla$ ) is projectively flat if and only if $\left(T^{*} M, g_{\nabla}\right)$ is locally conformally flat (see [3] for more details and references therein).

Let $\phi$ be a symmetric ( 0,2 )-tensor field on $M$. The twisted Riemannian extension is the neutral signature metric on $T^{*} M$ given by $[1,6]$

$$
g_{(\nabla, \phi)}=\left(\begin{array}{cc}
\phi_{i j}(u)-2 u_{k^{\prime}} \Gamma_{i j}^{k} & \delta_{i}^{j}  \tag{2.2}\\
\delta_{i}^{j} & 0
\end{array}\right),
$$

with respect to $\left\{\partial_{1}, \cdots, \partial_{n}, \partial_{1^{\prime}}, \cdots, \partial_{n^{\prime}}\right\},\left(i, j, k=1, \cdots, n ; k^{\prime}=k+n\right)$, where $\Gamma_{i j}^{k}$ are the Christoffel symbols of the torsion free affine connection $\nabla$ with respect to $\left(U, u_{i}\right)$.

As an example of twisted Riemannian extension metrics, we have the Walker metrics. The latter is detailed as follows. We say that a neutral signature pseudo-Riemannian metric $g$ of a $2 n$-dimensional manifold is a Walker metric if, locally, we have

$$
g=\left(\begin{array}{cc}
B & I_{n} \\
I_{n} & 0
\end{array}\right) .
$$

Thus, in particular, if the coefficients of the matrix $B$ are polynomial functions of order at most 1 in the $u_{i^{\prime}}$ variables, then $g$ is locally a twisted Riemannian extension; a twisted Riemannian extension is locally a Riemannian extension if $B$ vanishes on the zero-section. In these two instances, the linear terms in the $u_{i^{\prime}}$ variables give the connection 1-form of a torsion-free connection on the base manifold.

The non-zero Christoffel symbols $\widetilde{\Gamma}_{\alpha \beta}^{\gamma}$ of the Levi-Civita connection of the twisted Riemannian extension $g_{(\nabla, \phi)}$ are given by:

$$
\begin{aligned}
\widetilde{\Gamma}_{i j}^{k}= & \Gamma_{i j}^{k}, \quad \widetilde{\Gamma}_{i^{\prime} j}^{k^{\prime}}=-\Gamma_{j k}^{i} \quad \widetilde{\Gamma}_{i j^{\prime}}^{k^{\prime}}=-\Gamma_{i k}^{j}, \\
\widetilde{\Gamma}_{i j}^{k^{\prime}}= & \sum_{r} u_{r^{\prime}}\left(\partial_{k} \Gamma_{i j}^{r}-\partial_{i} \Gamma_{j k}^{r}-\partial_{j} \Gamma_{i k}^{r}+2 \sum_{l} \Gamma_{k l}^{r} \Gamma_{i j}^{l}\right) \\
& +\frac{1}{2}\left(\partial_{i} \phi_{j k}+\partial_{j} \phi_{i k}-\partial_{k} \phi_{i j}\right)-\sum_{l} \phi_{k l} \Gamma_{i j}^{l},
\end{aligned}
$$

where $(i, j, k, l, r=1, \cdots, n)$ and $\left(i^{\prime}=i+n, j^{\prime}=j+n, k^{\prime}=k+n, r^{\prime}=r+n\right)$. The non-zero components of the curvature tensor of $\left(T^{*} M, g_{(\nabla, \phi)}\right)$ up to the usual symmetries are given as follows: we omit $\widetilde{R}_{k j i}^{h^{\prime}}$, as it plays no role in our considerations.

$$
\widetilde{R}_{k j i}^{h}=R_{k j i}^{h}, \quad \widetilde{R}_{k j i}^{h^{\prime}}, \quad \widetilde{R}_{k j i^{\prime}}^{h^{\prime}}=-R_{k j h}^{i}, \quad \widetilde{R}_{k^{\prime} j i}^{h^{\prime}}=R_{h i j}^{k},
$$

where $R_{k j i}^{h}$ are the components of the curvature tensor of $(M, \nabla)$.

Twisted Riemannian extensions have nilpotent Ricci operator and hence, they are Einstein if and only if they are Ricci flat [6]. They can be used to construct non-flat Ricci flat pseudo-Riemannian manifolds.

The classical and twisted Riemannian extensions provide a link between the affine geometry of $(M, \nabla)$ and the neutral signature metric on $T^{*} M$. Some properties of the affine connection $\nabla$ can be investigated by means of the corresponding properties of the classical and twisted Riemannian extensions. For more details and information about classical Riemannian extensions and twisted Riemannian extensions, see [1, 2, 3, 6, 7] and references therein.

## 3. Szabó metrics on the cotangent bundle

In this section, we recall some basic definitions and results on affine Szabó manifolds [4]. Using the classical and twisted Riemannian extensions, we exhibit some examples of pseudo-Riemannian Szabó metrics of signature (3,3), which are not locally symmetric.
3.1. The affine Szabó manifolds. Let $(M, \nabla)$ be an $n$-dimensional smooth affine manifold, where $\nabla$ is a torsion-free affine connection on $M$. Let $\mathcal{R}^{\nabla}$ be the associated curvature operator of $\nabla$. We define the affine Szabó operator $\mathcal{S}^{\nabla}(X): T_{p} M \rightarrow T_{p} M$ with respect to a vector $X \in T_{p} M$ by

$$
\mathcal{S}^{\nabla}(X) Y:=\left(\nabla_{X} \mathcal{R}^{\nabla}\right)(Y, X) X
$$

3.1. Definition. [4] Let $(M, \nabla)$ be a smooth affine manifold.
(1) $(M, \nabla)$ is called affine Szabó at $p \in M$ if the affine Szabó operator $S^{\nabla}(X)$ has the same characteristic polynomial for every vector field $X$ on $M$.
(2) Also, $(M, \nabla)$ is called affine Szabó if $(M, \nabla)$ is affine Szabó at each point $p \in M$.
3.2. Theorem. [4] Let $(M, \nabla)$ be an $n$-dimensional affine manifold and $p \in M$. Then $(M, \nabla)$ is affine Szabó at $p \in M$ if and only if the characteristic polynomial of the affine Szabó operator $S^{\nabla}(X)$ is $P_{\lambda}\left(\mathcal{S}^{\nabla}(X)\right)=\lambda^{n}$, for every $X \in T_{p} M$.

This theorem leads to the following consequences which are proven in [4].
3.3. Corollary. [4] $(M, \nabla)$ is affine Szabó if the affine Szabó operators are nilpotent, i.e., 0 is the eigenvalue of $\mathcal{S}^{\nabla}(X)$ on the tangent bundle $T M$.
3.4. Corollary. [4] If $(M, \nabla)$ is affine Szabó at $p \in M$, then the Ricci tensor is cyclic parallel.

Affine Szabó connections are well-understood in 2-dimension, due to the fact that an affine connection is Szabó if and only if its Ricci tensor is cyclic parallel [4]. The situation is however more complicated in higher dimensions where the cyclic parallelism is a necessary but not sufficient condition for an affine connection to be Szabó.

According to Kowalski and Sekizawa [10], an affine manifold $(M, \nabla)$ is said to be an $L_{3}$-space if its Ricci tensor is cyclic parallel. Then, we have:
3.5. Theorem. Let $(M, \nabla)$ be a two-dimensional smooth torsion free affine manifold. Then, the following statements are equivalent:
(1) $(M, \nabla)$ is an affine Szabó manifold.
(2) $(M, \nabla)$ is a $L_{3}$-space.

In higher dimensions, it is not hard to see that there exist $L_{3}$-spaces which are not affine Szabó manifolds.

Next, we have an example of a real smooth manifold of three dimension in which the equivalence between Szabó and $L_{3}$ conditions holds. Let $M$ be a 3-dimensional smooth
manifold and $\nabla$ a torsion-free connection. We choose a fixed coordinates neighborhood $U\left(u_{1}, u_{2}, u_{3}\right) \subset M$.
3.6. Proposition. Let $M$ be a 3-dimensional manifold with torsion free connection given by

$$
\begin{equation*}
\nabla_{\partial_{1}} \partial_{1}=f_{1} \partial_{2}, \quad \nabla_{\partial_{2}} \partial_{2}=f_{2} \partial_{2}, \quad \nabla_{\partial_{3}} \partial_{3}=f_{3} \partial_{2} \tag{3.1}
\end{equation*}
$$

where $f_{i}=f_{i}\left(u_{1}, u_{2}, u_{3}\right)$, for $i=1,2,3$. Then $(M, \nabla)$ is affine Szabó if and only if the Ricci tensor of the affine connection (3.1) is cyclic parallel.

Proof. We denote the functions $f_{1}\left(u_{1}, u_{2}, u_{3}\right), f_{2}\left(u_{1}, u_{2}, u_{3}\right)$ and $f_{3}\left(u_{1}, u_{2}, u_{3}\right)$ by $f_{1}, f_{2}$ and $f_{3}$ respectively, if there is no risk of confusion. The Ricci tensor of the affine connection (3.1) expressed in the coordinates $\left(u_{1}, u_{2}, u_{3}\right)$ takes the form

$$
\begin{align*}
& \operatorname{Ric}^{\nabla}\left(\partial_{1}, \partial_{1}\right)=\partial_{2} f_{1}+f_{1} f_{2}, \quad \operatorname{Ric}^{\nabla}\left(\partial_{1}, \partial_{2}\right)=-\partial_{1} f_{2},  \tag{3.2}\\
& \operatorname{Ric}^{\nabla}\left(\partial_{3}, \partial_{2}\right)=-\partial_{3} f_{2}, \quad \operatorname{Ric}^{\nabla}\left(\partial_{3}, \partial_{3}\right)=\partial_{2} f_{3}+f_{2} f_{3} .
\end{align*}
$$

It is know that the Ricci tensor of any affine Szabó is cyclic parallel [4], it follows from the expressions in (3.2) and (3.3) that we have the following necessary condition for the affine connection (3.1) to be Szabó

$$
\begin{aligned}
& \partial_{1} \partial_{3} f_{2}=0, \\
& \partial_{1} \partial_{2} f_{2}-f_{2} \partial_{1} f_{2}=0, \\
& \partial_{3} \partial_{2} f_{2}-f_{2} \partial_{3} f_{2}=0, \\
& \partial_{1} \partial_{2} f_{1}+2 f_{1} \partial_{1} f_{2}+f_{2} \partial_{1} f_{1}=0, \\
& \partial_{2} \partial_{3} f_{3}+2 f_{3} \partial_{3} f_{2}+f_{2} \partial_{3} f_{3}=0, \\
& \partial_{2} \partial_{3} f_{1}+2 f_{1} \partial_{3} f_{2}+f_{2} \partial_{3} f_{1}=0, \\
& \partial_{2} \partial_{1} f_{3}+2 f_{3} \partial_{1} f_{2}+f_{2} \partial_{1} f_{3}=0, \\
& \partial_{2}^{2} f_{1}+f_{1} \partial_{2} f_{2}+f_{2} \partial_{2} f_{1}-\partial_{1}^{2} f_{2}=0, \\
& \partial_{2}^{2} f_{3}+f_{3} \partial_{2} f_{2}+f_{2} \partial_{2} f_{3}-\partial_{3}^{2} f_{2}=0 .
\end{aligned}
$$

Now, for each vector $X=\sum_{i=1}^{3} \alpha_{i} \partial_{i}$, a straightforward calculation shows that the associated affine Szabó operator is given by

$$
\left(\mathcal{S}^{\nabla}(X)\right)=\left(\begin{array}{ccc}
0 & 0 & 0  \tag{3.4}\\
a & 0 & c \\
0 & 0 & 0
\end{array}\right),
$$

with $a$ and $c$ are partial differential equations of $f_{1}, f_{2}$ and $f_{3}$. It follows from the matrix associated to $\mathcal{S}^{\nabla}(X)$, that its characteristic polynomial is written as follows: $P_{\lambda}\left[\mathcal{R}^{\nabla}(X)\right]=\lambda^{3}$. It follows that a affine connection given by (3.1) is affine Szabó if its Ricci tensor is cyclic parallel.
3.7. Example. The following connection on $\mathbb{R}^{3}$ defined by

$$
\begin{equation*}
\nabla_{\partial_{1}} \partial_{1}=u_{1} u_{3} \partial_{2}, \quad \nabla_{\partial_{2}} \partial_{2}=0, \quad \nabla_{\partial_{3}} \partial_{3}=\left(u_{1}+u_{3}\right) \partial_{2} \tag{3.5}
\end{equation*}
$$

is a non-flat affine Szabó connection.
3.2. Szabó pseudo-Riemannian manifolds. Let $(M, g)$ be a pseudo Riemannian manifold. The Szabó operator

$$
\mathcal{S}(X): Y \mapsto\left(\nabla_{X} R\right)(Y, X) X
$$

is a symmetric operator with $\mathcal{S}(X) X=0$. It plays an important role in the study of totally isotropic manifolds. Since $\mathcal{S}(\alpha X)=\alpha^{3} \mathcal{S}(X)$, the natural domains of definition for the Szabó operator are the pseudo-sphere bundles

$$
S^{ \pm}(M, g)=\{X \in T M, g(X, X)= \pm 1\}
$$

One says that $(M, g)$ is Szabó if the eigenvalues of $\mathcal{S}(X)$ are constant on the pseudospheres of unit timelike and spacelike vectors. The eigenvalue zero plays a distinguished role. One says that $(M, g)$ is nilpotent Szabó if $\operatorname{Spec}(\mathcal{S}(X))=\{0\}$ for all $X$. If $(M, g)$ is nilpotent Szabó of order 1, then ( $M, g$ ) is a local symmetric space (see [5] for more details).

Szabó in [12] used techniques from algebraic topology to show, in the Riemannian setting, that any such a metric is locally symmetric. He used this observation to prove that any two point homogeneous space is either flat or is a rank one symmetric space. Subsequently Gilkey and Stravrov [9] extended this result to show that any Szabó Lorentzian manifold has constant sectional curvature. However, for metrics of higher signature the situation is different. Indeed it was showed in [8] the existence of Szabó pseudoRiemannian manifolds endowed with metrics of signature $(p, q)$ with $p \geq 2$ and $q \geq 2$ which are not locally symmetric .

Next, we use the classical and twisted Riemannian extensions to construct some pseudo-Riemannian metrics on $\mathbb{R}^{6}$ which are nilpotent Szabó of order $\geq 2$.
3.3. Riemannian extensions of an affine Szabó connection. We start with the following result.
3.8. Theorem. Let $(M, \nabla)$ be a smooth torsion-free affine manifold. Then the following statements are equivalent:
(i) $(M, \nabla)$ is affine Szabó.
(ii) The Riemannian extension $\left(T^{*} M, g_{\nabla}\right)$ of $(M, \nabla)$ is a pseudo Riemannian Szabó manifold.

Proof. Let $\tilde{X}=\alpha_{i} \partial_{i}+\alpha_{i^{\prime}} \partial_{i^{\prime}}$ be a vector field on $T^{*} M$. Then the matrix of the Szabó operator $\tilde{S}(\tilde{X})$ with respect to the basis $\left\{\partial_{i}, \partial_{i^{\prime}}\right\}$ is of the form

$$
\tilde{\mathcal{S}}(\tilde{X})=\left(\begin{array}{cc}
\mathcal{S}^{\nabla}(X) & 0 \\
* & t^{\nabla}(X)
\end{array}\right)
$$

where $\mathcal{S}^{\nabla}(X)$ is the matrix of the affine Szabó operator on $M$ relative to the basis $\left\{\partial_{i}\right\}$. Note that the characteristic polynomial $P_{\lambda}[\tilde{\mathcal{S}}(\tilde{X})]$ of $\tilde{\mathcal{S}}(\tilde{X})$ and $P_{\lambda}\left[\mathcal{S}^{\nabla}(X)\right]$ of $\mathcal{S}^{\nabla}(X)$ are related by

$$
\begin{equation*}
P_{\lambda}[\tilde{\mathcal{S}}(\tilde{X})]=P_{\lambda}\left[\mathcal{S}^{\nabla}(X)\right] \cdot P_{\lambda}\left[{ }^{t} \mathcal{S}^{\nabla}(X)\right] . \tag{3.6}
\end{equation*}
$$

Now, if the affine manifold $(M, \nabla)$ is assumed to be affine Szabó, then $\mathcal{S}^{\nabla}(X)$ has zero eigenvalues for each vector field $X$ on $M$. Therefore, it follows from (3.6) that the eigenvalues of $\tilde{\mathcal{S}}(\tilde{X})$ vanish for every vector field $\tilde{X}$ on $T^{*} M$. Thus $\left(T^{*} M, g_{\nabla}\right)$ is pseudoRiemannian Szabó manifold.
Conversely, assume that $\left(T^{*} M, g_{\nabla}\right)$ is an pseudo-Riemannian Szabó manifold. If $X=$ $\alpha_{i} \partial_{i}$ is an arbitrary vector field on $M$ then $\tilde{X}=\alpha_{i} \partial_{i}+\frac{1}{2 \alpha_{i}} \partial_{i^{\prime}}$ is an unit vector field at every point of the zero section on $T^{*} M$. Then from (3.6), we see that, the characteristic polynomial $P_{\lambda}[\tilde{\mathcal{S}}(\tilde{X})]$ of $\tilde{\mathscr{S}}(\tilde{X})$ is the square of the characteristic polynomial $P_{\lambda}\left[\mathcal{S}^{\nabla}(X)\right]$ of $S^{\nabla}(X)$. Since for every unit vector field $\tilde{X}$ on $T^{*} M$ the characteristic polynomial
$P_{\lambda}[\tilde{S}(\tilde{X})]$ should be the same, it follows that for every vector field $X$ on $M$ the characteristic polynomial $P_{\lambda}\left[S^{\nabla}(X)\right]$ is the same. Hence $(M, \nabla)$ is affine Szabó.

As an example, we have the following. Let $(M, \nabla)$ be a 3 -dimensional affine manifold. Let $\left(u_{1}, u_{2}, u_{3}\right)$ be local coordinates on $M$. We write $\nabla_{\partial_{i}} \partial_{j}=\sum_{k} \Gamma_{i j}^{k} \partial_{k}$ for $i, j, k=$ $1,2,3$ to define the coefficients of affine connection $\nabla$. If $\omega \in T^{*} M$, we write $\omega=$ $u_{4} d u_{1}+u_{5} d u_{2}+u_{6} d u_{3}$ to define the dual fiber coordinates ( $u_{4}, u_{5}, u_{6}$ ), and thereby obtain canonical local coordinates $\left(u_{1}, u_{2}, u_{3}, u_{4}, u_{5}, u_{6}\right)$ on $T^{*} M$. The Riemannian extension is the metric of neutral signature $(3,3)$ on the cotangent bundle $T^{*} M$ locally given by

$$
\begin{aligned}
& g_{\nabla}\left(\partial_{1}, \partial_{4}\right)=g_{\nabla}\left(\partial_{2}, \partial_{5}\right)=g_{\nabla}\left(\partial_{3}, \partial_{6}\right)=1, \\
& g_{\nabla}\left(\partial_{1}, \partial_{1}\right)=-2 u_{4} \Gamma_{11}^{1}-2 u_{5} \Gamma_{11}^{2}-2 u_{6} \Gamma_{11}^{3}, \\
& g_{\nabla}\left(\partial_{1}, \partial_{2}\right)=-2 u_{4} \Gamma_{12}^{1}-2 u_{5} \Gamma_{12}^{2}-2 u_{6} \Gamma_{12}^{3}, \\
& g_{\nabla}\left(\partial_{1}, \partial_{3}\right)=-2 u_{4} \Gamma_{13}^{1}-2 u_{5} \Gamma_{13}^{2}-2 u_{6} \Gamma_{13}^{3}, \\
& g_{\nabla}\left(\partial_{2}, \partial_{2}\right)=-2 u_{4} \Gamma_{22}^{1}-2 u_{5} \Gamma_{22}^{2}-2 u_{6} \Gamma_{22}^{3}, \\
& g_{\nabla}\left(\partial_{2}, \partial_{3}\right)=-2 u_{4} \Gamma_{23}^{1}-2 u_{5} \Gamma_{23}^{2}-2 u_{6} \Gamma_{23}^{3}, \\
& g_{\nabla}\left(\partial_{3}, \partial_{3}\right)=-2 u_{4} \Gamma_{33}^{1}-2 u_{5} \Gamma_{33}^{2}-2 u_{6} \Gamma_{33}^{3} .
\end{aligned}
$$

From Example 3.7, the Riemannian extension of the affine connection defined in (3.5) is the pseudo-Riemannian metric given by

$$
\begin{align*}
g= & 2 d u_{1} \otimes d u_{4}+2 d u_{2} \otimes d u_{5}+2 d u_{3} \otimes d u_{6} \\
& -2\left(u_{1} u_{3} u_{5}\right) d u_{1} \otimes d u_{1}-2\left(u_{1}+u_{3}\right) u_{5} d u_{3} \otimes d u_{3} . \tag{3.7}
\end{align*}
$$

This metric leads to the following result.
3.9. Proposition. The metric in (3.7) is Szabó of signature $(3,3)$ with zero eigenvalues. Moreover, it is not locally symmetric.

Proof. The non-vanishing components of the curvature tensor of $\left(\mathbb{R}^{6}, g_{\nabla}\right)$ are given by $R\left(\partial_{1}, \partial_{3}\right) \partial_{1}=-u_{1} \partial_{2}, R\left(\partial_{1}, \partial_{3}\right) \partial_{3}=\partial_{2}, R\left(\partial_{1}, \partial_{3}\right) \partial_{5}=u_{1} \partial_{4}-\partial_{6}, R\left(\partial_{1}, \partial_{5}\right) \partial_{1}=-u_{1} \partial_{6}$, $R\left(\partial_{1}, \partial_{5}\right) \partial_{3}=u_{1} \partial_{4}, R\left(\partial_{3}, \partial_{5}\right) \partial_{1}=\partial_{6}, R\left(\partial_{3}, \partial_{5}\right) \partial_{3}=-\partial_{4}$. Let $X=\sum_{i=1}^{6} \alpha_{i} \partial_{i}$ be a non-zero vector on $\mathbb{R}^{6}$. Then the matrix associated with the Szabó operator $\mathcal{S}(X):=$ $\left(\nabla_{X} \mathcal{R}\right)(\cdot, X) X$ is given by

$$
(\mathcal{S}(X))=\left(\begin{array}{cccccc}
0 & 0 & 0 & 0 & 0 & 0 \\
-1 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
2 & 0 & -1 & 0 & -1 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
-1 & 0 & 1 & 0 & 1 & 0
\end{array}\right)
$$

Hence the characteristic polynomial of the Szabó operators is $P_{\lambda}(S(X))=\lambda^{6}$. Since one of the components of $\nabla R,\left(\nabla_{\partial_{1}} R\right)\left(\partial_{1}, \partial_{3}, \partial_{5}, \partial_{1}\right)=1$ is non-zero, the metric in (3.7) is not locally symmetric. The proof is completed.
3.4. Twisted Riemannian extensions of an affine Szabó connection. In this subsection, we study the twisted Riemannian extensions which is a generalization of classical Riemannian extensions. We have following result.
3.10. Theorem. Let $\left(T^{*} M, g_{\nabla, \phi}\right)$ be the cotangent bundle of an affine manifold ( $M, \nabla$ ) equipped with the twisted Riemannian extension.

Then $\left(T^{*} M, g_{(\nabla, \phi)}\right)$ is a pseudo-Riemannian Szabó manifold if and only $(M, \nabla)$ is affine Szabó for any symmetric (0,2)-tensor field $\phi$.

As an example we have the following.
3.11. Example. Let us consider the twisted Riemannian extensions of the affine connection $\nabla$ given in Example 3.7. This is given by

$$
\begin{align*}
g & =2 d u_{1} \otimes d u_{4}+2 d u_{2} \otimes d u_{5}+2 d u_{3} \otimes d u_{6}+2 \phi_{12} d u_{1} \otimes d u_{2} \\
& +2 \phi_{13} d u_{1} \otimes d u_{3}+2 \phi_{23} d u_{2} \otimes d u_{3}+\left(\phi_{11}-2 u_{1} u_{3} u_{5}\right) d u_{1} \otimes d u_{1} \\
& +\phi_{22} d u_{2} \otimes d u_{2}+\left[\phi_{33}-2\left(u_{1}+u_{3}\right) u_{5}\right] d u_{3} \otimes d u_{3}, \tag{3.8}
\end{align*}
$$

where $\left(u_{1}, u_{2}, \cdots, u_{6}\right)$ are coordinates in $\mathbb{R}^{6}$. The non-zero Christoffel symbols are as follows:

$$
\begin{aligned}
& \Gamma_{11}^{2}=-\Gamma_{15}^{4}=u_{1} u_{3}, \quad \Gamma_{11}^{4}=\frac{1}{2} \partial_{1} \phi_{11}-u_{3} u_{5}-u_{1} u_{3} \phi_{12}, \\
& \Gamma_{11}^{5}=\partial_{1} \phi_{12}-\frac{1}{2} \partial_{2} \phi_{11}-u_{1} u_{3} \phi_{22}, \quad \Gamma_{11}^{6}=\partial_{1} \phi_{13}+u_{5} u_{1}-\frac{1}{2} \partial_{3} \phi_{11}-u_{1} u_{3} \phi_{22}, \\
& \Gamma_{12}^{4}=\frac{1}{2} \partial_{2} \phi_{11}, \Gamma_{12}^{5}=\frac{1}{2} \partial_{1} \phi_{22}, \Gamma_{12}^{6}=\frac{1}{2}\left\{\partial_{2} \phi_{13}+\partial_{1} \phi_{23}-\partial_{3} \phi_{12}\right\}, \\
& \Gamma_{13}^{4}=-u_{5} u_{1}+\frac{1}{2} \partial_{3} \phi_{11}, \quad \Gamma_{13}^{5}=\frac{1}{2}\left\{\partial_{3} \phi_{12}+\partial_{1} \phi_{32}-\partial_{2} \phi_{13}\right\}, \\
& \Gamma_{13}^{6}=-u_{5}+\frac{1}{2} \partial_{1} \phi_{33}, \quad \Gamma_{22}^{4}=\partial_{2} \phi_{21}-\frac{1}{2} \partial_{1} \phi_{22}, \quad \Gamma_{22}^{5}=\frac{1}{2} \partial_{2} \phi_{22}, \\
& \Gamma_{22}^{6}=\partial_{2} \phi_{23}-\frac{1}{2} \partial_{3} \phi_{22}, \Gamma_{23}^{4}=\frac{1}{2}\left\{\partial_{3} \phi_{21}+\partial_{2} \phi_{31}-\partial_{1} \phi_{23}\right\}, \\
& \Gamma_{23}^{5}=\frac{1}{2} \partial_{3} \phi_{22}, \quad \Gamma_{23}^{6}=\frac{1}{2} \partial_{2} \phi_{33}, \Gamma_{33}^{2}=-\Gamma_{35}^{6}=\left(u_{1}+u_{3}\right), \\
& \Gamma_{33}^{4}=\partial_{3} \phi_{31}+u_{5}-\frac{1}{2} \partial_{1} \phi_{33}-\left(u_{1}+u_{3}\right) \phi_{12}, \\
& \Gamma_{33}^{5}=\partial_{3} \phi_{32}-\frac{1}{2} \partial_{2} \phi_{33}-\left(u_{1}+u_{3}\right) \phi_{22}, \Gamma_{33}^{5}=-u_{5}+\partial_{3} \phi_{33}-\left(u_{1}+u_{3}\right) \phi_{32} .
\end{aligned}
$$

For $X=\sum_{i=1}^{6} \alpha_{i} \partial_{i}$, by a straightforward calculation the characteristic polynomial associated with the Szabó operator is $P_{\lambda}[S(X)]=\lambda^{6}$. So, $\left(M, g_{\nabla, \phi}\right)$ is a pseudo-Riemannian Szabó metric of signature ( 3,3 ) with zero eigenvalue.

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